



# RSF Elektronik

www.rsf.at

MS 15

EXPOSED LINEAR ENCODERS  
WITH HOMING AND LIMIT FUNCTION





## SPECIAL FEATURES

- Online signal stabilization
- Display of the signal quality directly at the scanning head via 3-coloured LED function
- Permanent control of the signals over the whole measuring length
- High quality of the signals due to singlefield scanning
- Homing and limit function
- Reference mark position customizable

## TERM EXPLANATIONS

### Grating period

A grating is a continuous series of lines and spaces printed on the graduation carrier. The width of one line and one space is called the period of the grating. The lines and spaces are accurately placed on the graduation carrier.

### Signal period

When scanning the grating, the scanning head produces sinusoidal signals with a period equal to the grating period.

### Interpolation

The sinusoidal signal period can be electronically divided into equal parts. The interpolation circuitry generates a square-wave edge for each division.

### Measuring step

The smallest digital counting step produced by an encoder.

### Yaw angle, pitch angle, roll angle, displacement, gap tolerance

Mounting tolerances of the scanning head relative to the graduation carrier.

### Reference pulse (reference mark)

There is an additional track of marks printed next to the grating to allow a user to find an absolute position along the length of the graduation carrier. A one increment wide signal is generated when the scanning head passes the reference mark on the graduation carrier.

This is called a "true" reference mark since it is repeatable in both directions. Subsequent electronics use this pulse to assign a preset value to the absolute reference mark position.

### Fault detection signal ( $\overline{US}$ )

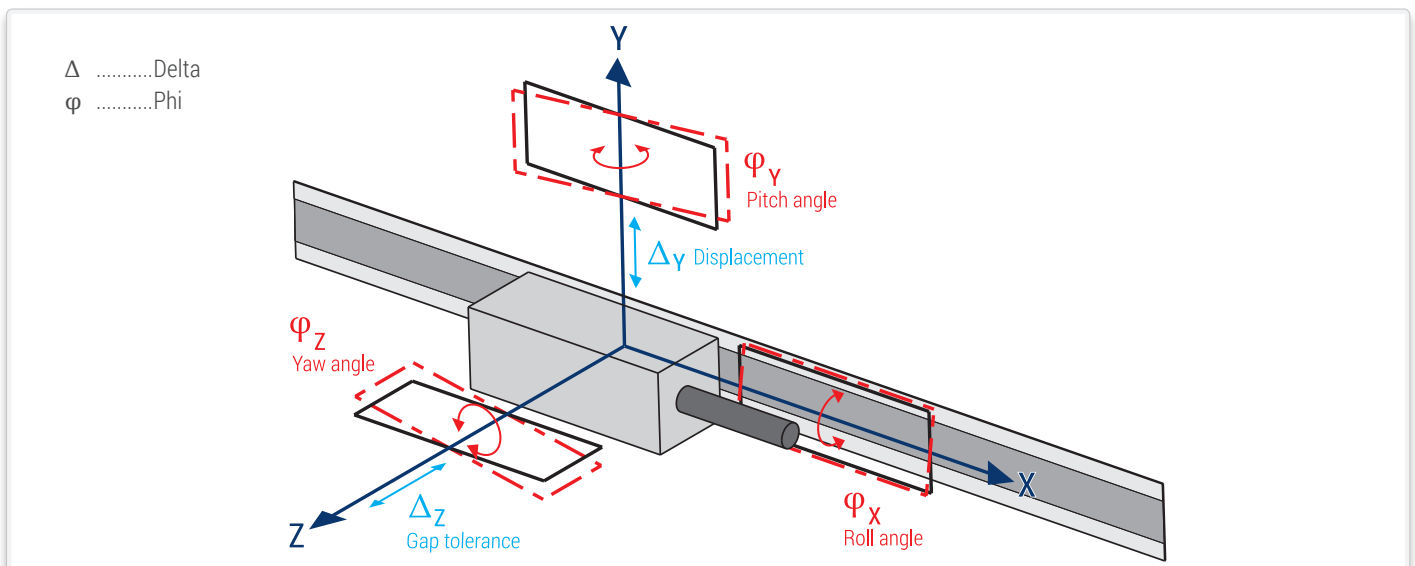
The fault detection signal indicates fault conditions such as an interruption in the supply lines, failure of the light source, etc. For example, it can be used in the automated production for the machine switch-off.

### Online signal stabilization (HSP)

During moving the amplitude, offset-error, amplitude differences and phase shift error are measured and stabilized cyclic.

### Abbe error

Measuring error due to lateral distance between the measuring system and the machining level.



## PERFORMANCE CHARACTERISTICS

- CONTAMINATION RESISTANCE
- IMMUNITY AGAINST AGING AND TEMPERATURE CHANGES
- HIGH PERMISSIBLE TRAVERSING SPEED
- EASY MOUNTING
- SMALL DIMENSIONS
- NO MECHANICAL BACKLASH
- NO FRICTIONAL FORCE
- REFERENCE MARKS REPEATABLE FROM BOTH TRAVERSING DIRECTIONS
- TWO SEPARATE SWITCH SIGNALS
- RESOLUTION: 10  $\mu\text{m}$  – 0.05  $\mu\text{m}$



**MS 15 MEETS ALL THESE REQUIREMENTS!**

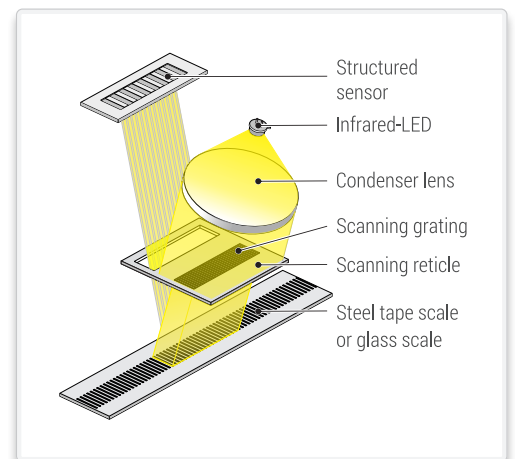
## SCANNING PRINCIPLE

The model MS 15 incremental linear encoder system works with the photoelectric measuring principle and a **singlefield reflective scanning method**.

The regulated light of an infrared LED is collimated by a condenser lens and passes through the grid of the reticle. After being reflected from the graduation carrier, the infrared LED generates a periodic intensity distribution on the structured sensor.

The sensor generates high quality sinusoidal signals which are highly insensitive to possible contaminations.

The regulation of the LED ensures a constant signal amplitude, guaranteeing stability in the case of temperature fluctuations and with long-run operation.

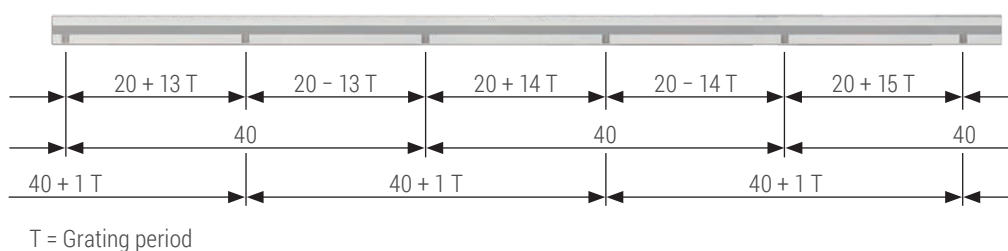


## REFERENCE MARKS

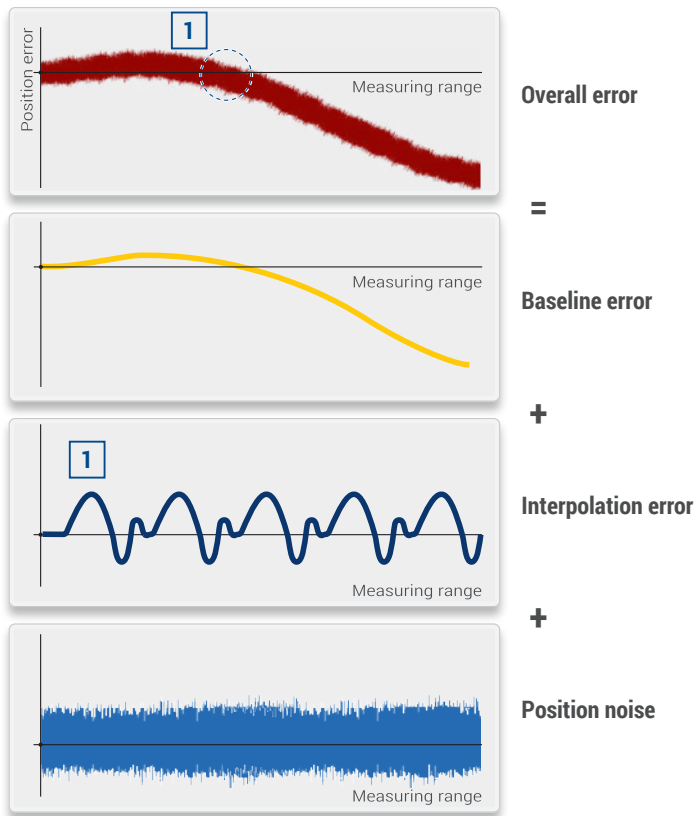
Principle of the standard reference marks



Principle of the distance-coded reference marks



## ACCURACY DEFINITION



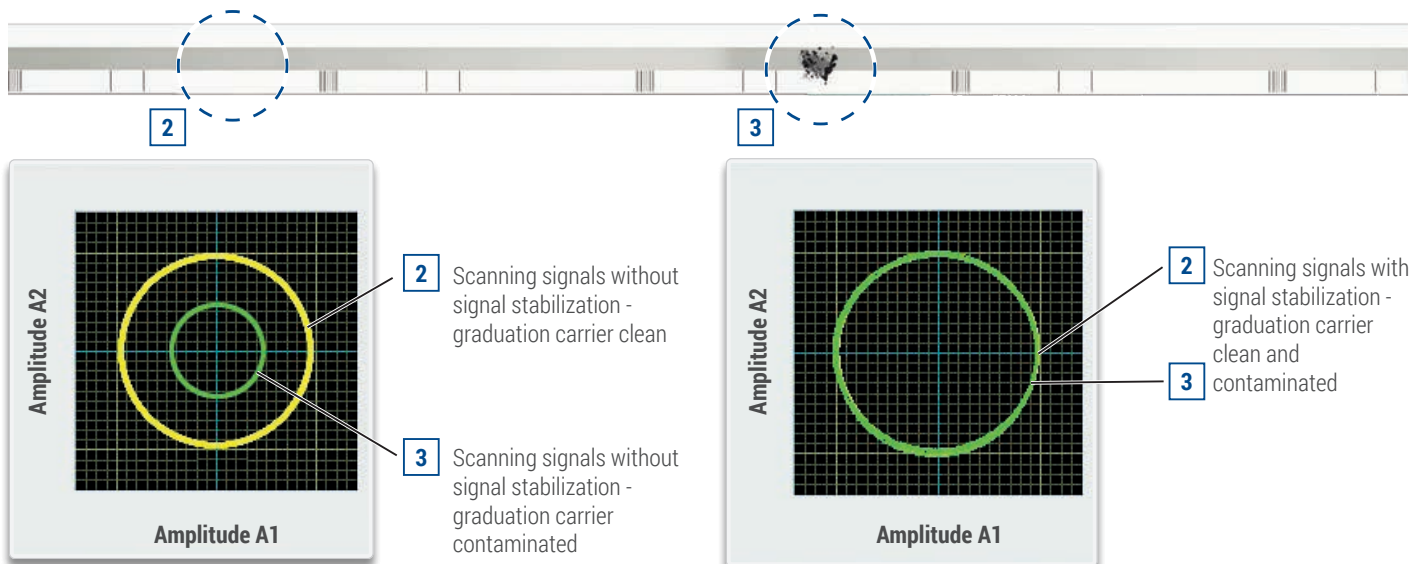
The accuracy of a linear encoder is mainly determined by the baseline error of the graduation carrier, the interpolation error of the optoelectronic scanning and the position noise.

The baseline error is the error of the graduation carrier identified in a measurement room under optimum conditions, along a determined measuring length, without any interpolation error and position noise.

The indicated accuracy grade represents the maximum possible baseline error. It is calculated within any section with a maximum length of one meter.

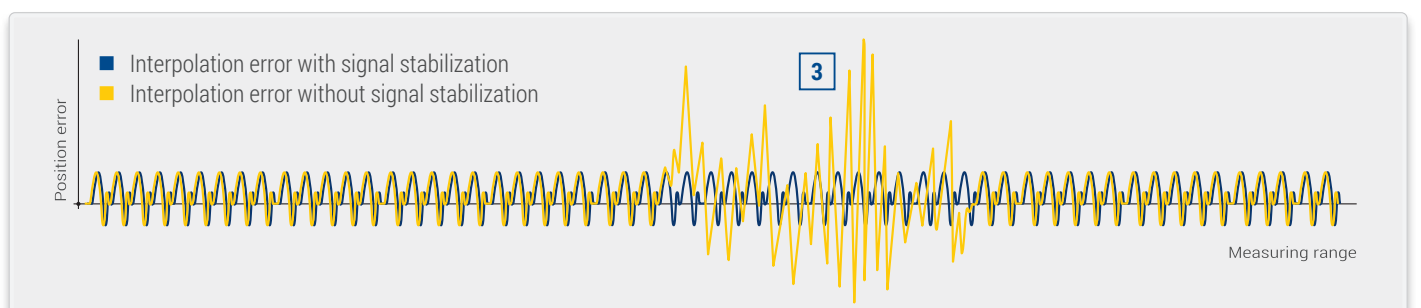
### Effect of contamination on the quality and amplitude of scanning signal

Graduation carrier contaminated by fluids, dust, particles, fingerprints etc.

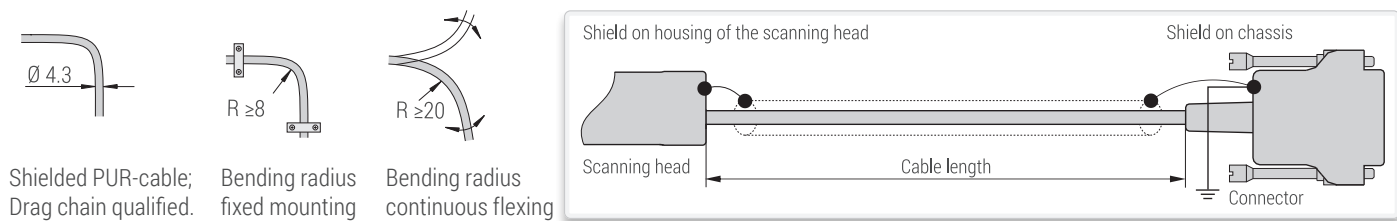


### Effect of contamination on the interpolation error

Graduation carrier contaminated by fluids, dust, particles, fingerprints etc.



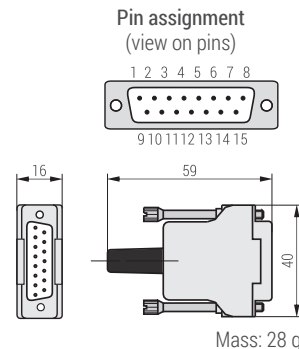
# SHIELDING, PIN ASSIGNMENT



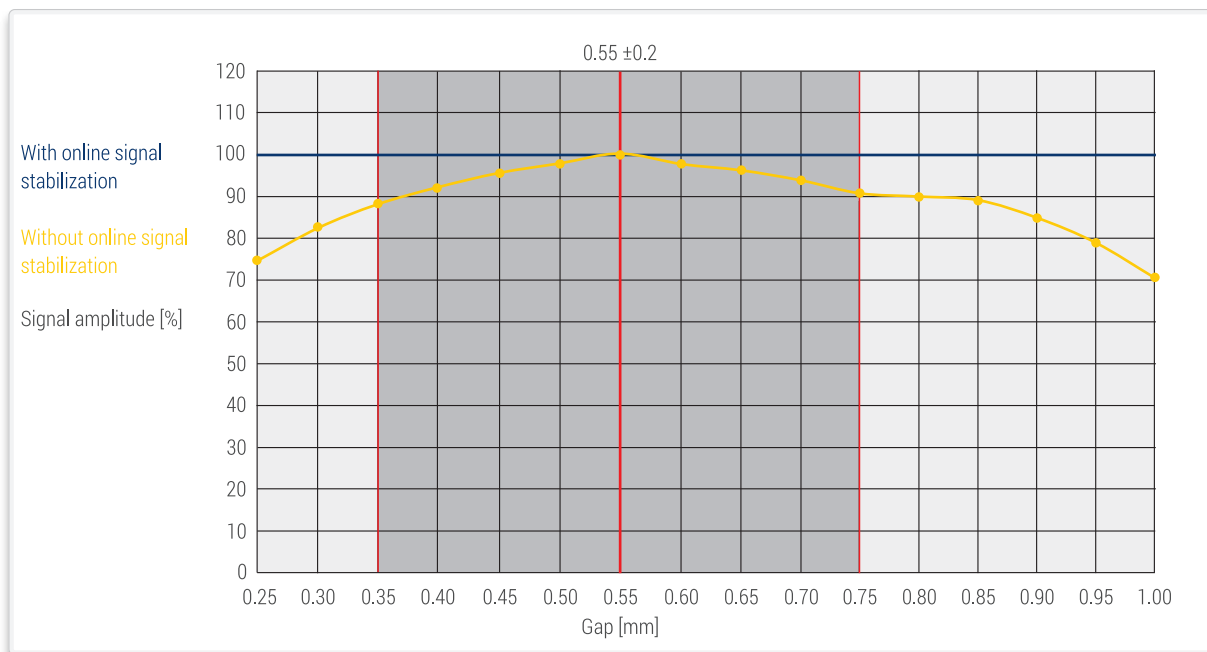
## D-sub connector, male, 15-pin

Pin	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Sinusoidal voltage signals 1 Vpp	Test**	0 V Sensor	Occupied	RI-	A2-	A1-	V+ Sensor	V+	0 V	S1***	S2***	RI+	A2+	A1+	nc
Square-wave signals via line driver	Test*	0 V Sensor	US	RI	T2	T1	V+ Sensor	V+	0 V	S1***	S2***	RI	T2	T1	nc

- \* Test = analog signal switch-over for set-up. By applying +5 V to the test pin, the test signals (sinusoidal micro-current signals 11 µApp) are switched to the output connector.
- \*\* Test = analog signal switch-over for set-up. By applying +5 V to the test pin, the NOT corrected test signals (1 Vpp) are switched to the output connector.
- S1, S2 = switch signals.
- \*\*\* Version without switch signals (version K) = without function.
- Sensor: the sensor pins are bridged in the chassis with the particular power supply.
- The shield is connected with the chassis.
- Pins or wires marked "occupied" or "nc" must not be used by the customer.



## Effect of the scanning head gap on the signal amplitude



# INTERFACES

## SINUSOIDAL VOLTAGE SIGNALS 1 VPP

(drawing shows "positive counting direction")

**Power supply:** +5V ±10 %, max. 160 mA (unloaded)

**Track signals** (differential voltage A1+ to A1- resp. A2+ to A2-):

Signal amplitude 0.6 Vpp to 1.2 Vpp; typ. 1 Vpp

(with terminating impedance  $Z_0 = 120 \Omega$  between A1+ to A1- resp. A2+ to A2-).

**Reference mark** (differential voltage RI+ to RI-):

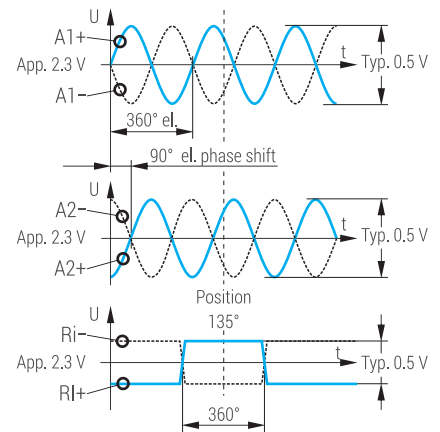
Square-wave pulse with an amplitude of 0.8 up to 1.2 V; typical 1 V

(with terminating impedance  $Z_0 = 120 \Omega$  between RI+ to RI-)

**Advantage:**

- High permissible traversing speed with long cable lengths possible.

### Voltage signals (1 Vpp)



## SQUARE-WAVE SIGNALS

(drawing shows "positive counting direction")

With the integrated interpolation electronics (for times -1, -5, -10, -20, -25, -50, -100 or -200) the photoelement output signals are converted into two square-wave signals that have a phase shift of 90°.

The output signals are „differential“ via line driver (RS 422). One measuring step reflects the measuring distance between two edges of the square-wave signals.

The controls/DRO's must be able to detect each edge of the square-wave signals. The minimum edge separation  $a_{min}$  is listed in the technical data and refers to a measurement at the output of the interpolator (inside the scanning head). Propagation-time differences in the line driver, the cable and the line receiver reduce the edge separation.

**Propagation-time differences:**

Line driver: max. 10 ns

Cable: 0.2 ns/m

Line receiver: max. 10 ns (referred to the recommended line receiver circuit)

To prevent counting errors, the controls/DRO's must be able to process the resulting edge separation.

**Example:**

$a_{min} = 100$  ns, 10 m cable

$100 \text{ ns} - 10 \text{ ns} - 10 \times 0.2 \text{ ns} - 10 \text{ ns} = 78 \text{ ns}$

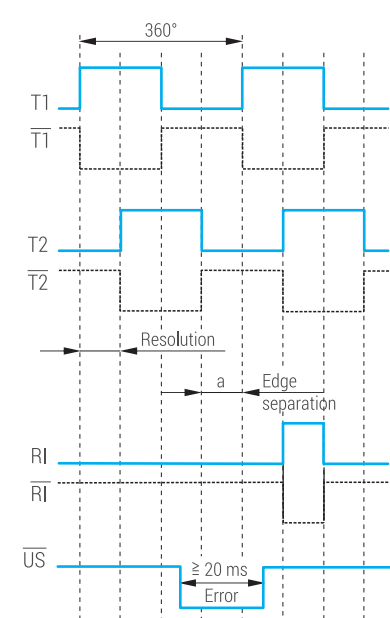
**Power supply:** +5V ±10 %, max. 160 mA (unloaded)

**Advantages:**

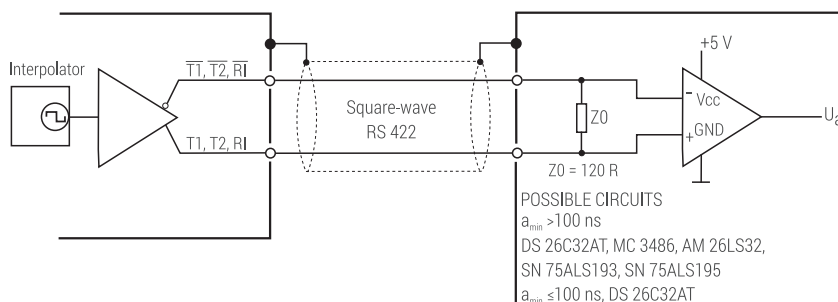
- Noise immune signals.

- No further subdividing electronics necessary.

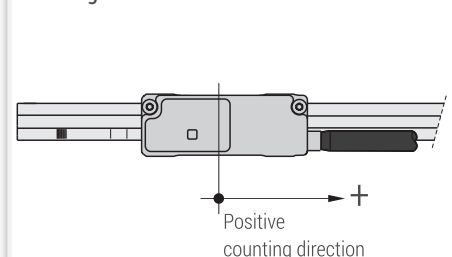
### Square-wave signals „differential“



### Recommended line receiver circuit



### Counting direction

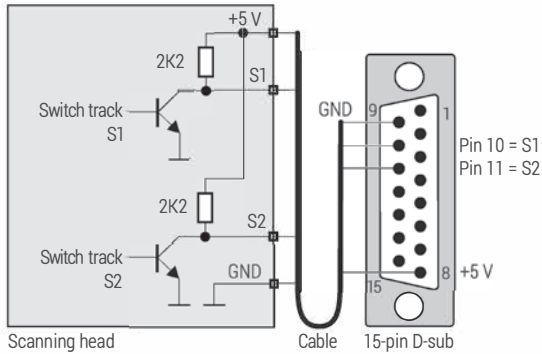


# SWITCH SIGNAL OUTPUT

For individual special functions there are two additional switch tracks on the steel tape scale.  
The switching point position can be chosen by the user by placing self-adhesive covering tapes.

## VERSION H

TTL output (active high)

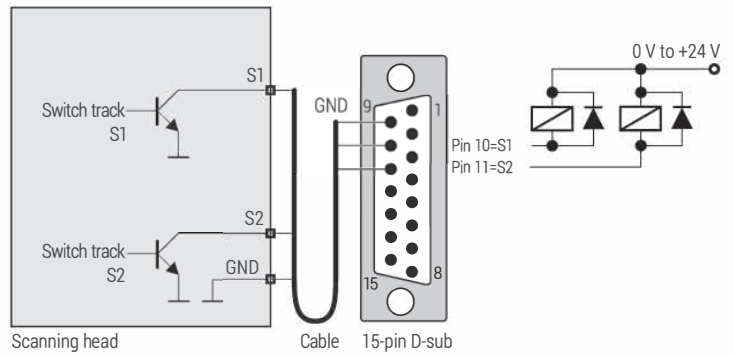


S1, S2 = TTL output  
 $I_{SOURCE} = 1 \text{ mA}$  (high level  $> 2 \text{ V}$ )  
 $I_{SINK} = 20 \text{ mA}$  (low level  $< 0.8 \text{ V}$ )



## VERSION Z

Open collector output (active high impedance)

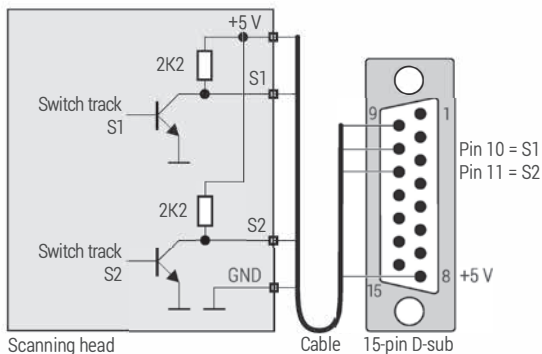


S1, S2 = open collector output  
 $I_{SINK} = 20 \text{ mA}$  (low level  $< 0.8 \text{ V}$ )



## VERSION L

TTL output (active low)

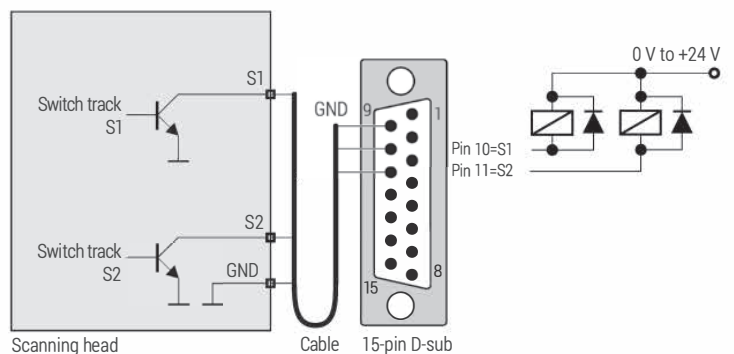


S1, S2 = TTL output  
 $I_{SOURCE} = 1 \text{ mA}$  (high level  $> 2 \text{ V}$ )  
 $I_{SINK} = 20 \text{ mA}$  (low level  $< 0.8 \text{ V}$ )



## VERSION C

Open collector output (active low)



S1, S2 = open collector output  
 $I_{SINK} = 20 \text{ mA}$  (low level  $< 0.8 \text{ V}$ )



## TECHNICAL DATA

### SCANNING HEAD

Model	AK MS 15 1 Vpp	AK MS 15 TTLx1u	AK MS 15 TTLx5	AK MS 15 TTLx10	AK MS 15 TTLx20	AK MS 15 TTLx25	AK MS 15 TTLx50	AK MS 15 TTLx100	AK MS 15 TTLx200
Interface	~	⌋	⌋	⌋	⌋	⌋	⌋	⌋	⌋
Measuring step [μm]	Depending on external interpolation	10.00	2.00	1.00	0.50	0.40	0.20	0.10	0.05
Integrated interpolation	--	Times 1	Times 5	Times 10	Times 20	Times 25	Times 50	Times 100	Times 200
Max. output frequency [kHz]	250	--	--	--	--	--	--	--	--
Velocity typ. [m/s]	10.00	10.00	6.40	3.20	2.40	1.92	1.92	0.96	0.96
Edge separation a <sub>min</sub> [ns]	--	500	300	300	200	200	100	100	50
Velocity max. [m/s]	10.00	10.00	9.60	9.60	9.60	9.60	4.80	2.40	1.20
Edge separation a <sub>min</sub> [ns]	--	500	200	100	50	40	40	40	40
Interpolation error with signal stabilization	Typical ±65 nm (peak-peak)								
Electrical connection	Cable, 0.5 m, 1 m or 3 m with D-sub connector, male, 15-pin								
Voltage supply	+5 V ±10 %								
Power consumption	Max. 880 mW (without load)								
Current consumption	Max. 160 mA (without load)								
Vibration 55 Hz – 2000 Hz Shock 8 ms	≤ 150 m/s <sup>2</sup> (EN 60 068-2-6) ≤ 750 m/s <sup>2</sup> (EN 60 068-2-27)								
Operating temperature Storage temperature	0 °C to 50 °C -20 °C to 70 °C								
Mass	Scanning head: 12 g (without cable), cable: 30 g/m, connector: D-sub connector: 28 g								

### GRADUATION CARRIER

Model	MB MS 15 MK	MS 15 MP	MS 15 GK	MS 15 BK
Graduation carrier	Steel tape scale	Steel tape scale	Glass scale	Glass ceramic scale
Coefficient of linear expansion	$\alpha \approx 10 \times 10^{-6}/K$	$\alpha \approx 10 \times 10^{-6}/K$	$\alpha \approx 8.5 \times 10^{-6}$	$\alpha \approx 0 \times 10^{-6} / K$
Grating period	40 μm	40 μm	40 μm	40 μm
Accuracy grades *	±5, ±15 μm/m	±5, ±15 μm/m	±3, ±5 μm/m	±3, ±5 μm/m
Non-linearity *	±3 μm/m	±3 μm/m	±3 μm/m	±3 μm/m
Baseline error	≤ ±0.75 μm/50 mm (typical)	≤ ±0.75 μm/50 mm (typical)	≤ ±0.30 μm/10 mm	≤ ±0.30 μm/10 mm
Measuring length ML	20 000 mm	20 000 mm	3140 mm	1920 mm **
Reference marks	Standard: 50 mm equidistant / Position selectable by customer / Distance-coded on request			
Mass	17 g/m	90 g/m + 2 g clamping	55 g/m	57 g/m

\* At 20 °C

\*\* Longer lengths on request

### CONFORMITIES AND CERTIFICATIONS

RoHS	2011/65/EU, 2015/863/EU
EMV	2014/30/EU
Product-Certifications	UL, CSA, EN, IEC 61010-1

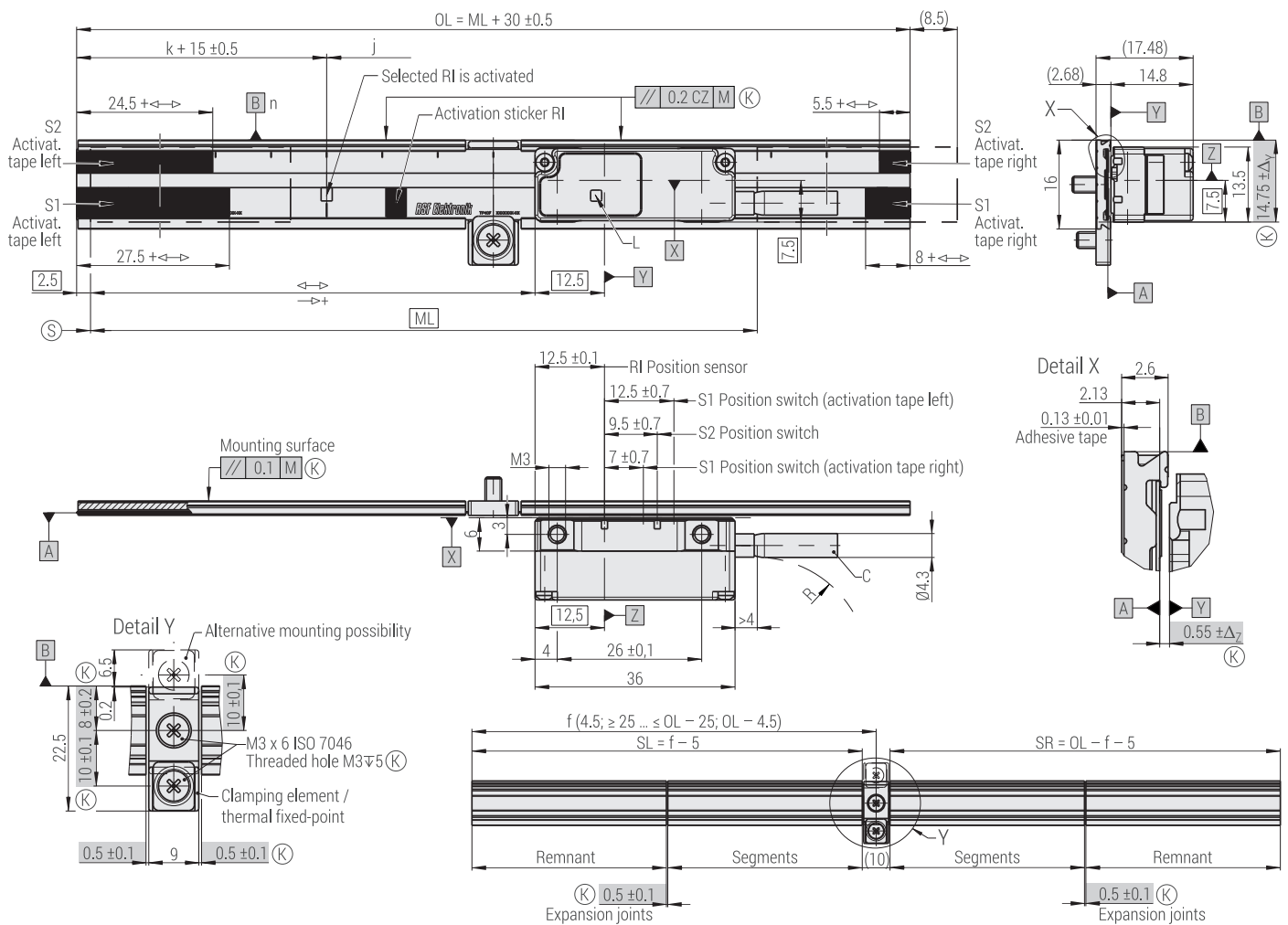


## MS 15 MP

- Steel tape scale in aluminum carrier with clamping element
- Clamping element bolted
- Carrier with adhesive tape



Dimensions, mounting tolerances:



- M = Machine guideway
- ML = Measuring length
- OL = Overall length
- $\leftarrow \rightarrow$  = 0...ML
- $\rightarrow +$  = Direction of motion of the scanning head for ascending position values
- RI = Selectable reference mark(s)
- k = Any position of the selected reference mark from the beginning of the ML
- j = Additional reference marks selectable every 50 mm
- f = Position of the clamping element  
Standard:  $f = OL/2$   
Optional:  $f = \begin{cases} 4.5 \\ \geq 25 \dots \leq OL - 25 \\ OL - 4.5 \end{cases}$
- C = Cable
- (K) = Required mating dimensions
- L = LED function control
- R = Bending radius: stat.  $R \geq 8$  mm, dyn.  $R \geq 20$  mm
- (S) = Beginning of the measuring length
- S1, S2 = Switch signal
- n = 1, 2, 3 ... (number of segments)

- Permissible position deviation scanning head - tape scale (A/B)
- $\Delta_Y$  = Displacement,  $\pm 0.5$  mm
  - $\Delta_Z$  = Gap tolerance,  $\pm 0.2$  mm
  - $\varphi_Z$  =  $\pm 1.00$  mrad or  $\pm 0.06^\circ$  (yaw angle)
  - $\varphi_Y$  =  $\pm 3.50$  mrad or  $\pm 0.20^\circ$  (pitch angle)
  - $\varphi_X$  =  $\pm 4.00$  mrad or  $\pm 0.23^\circ$  (roll angle)

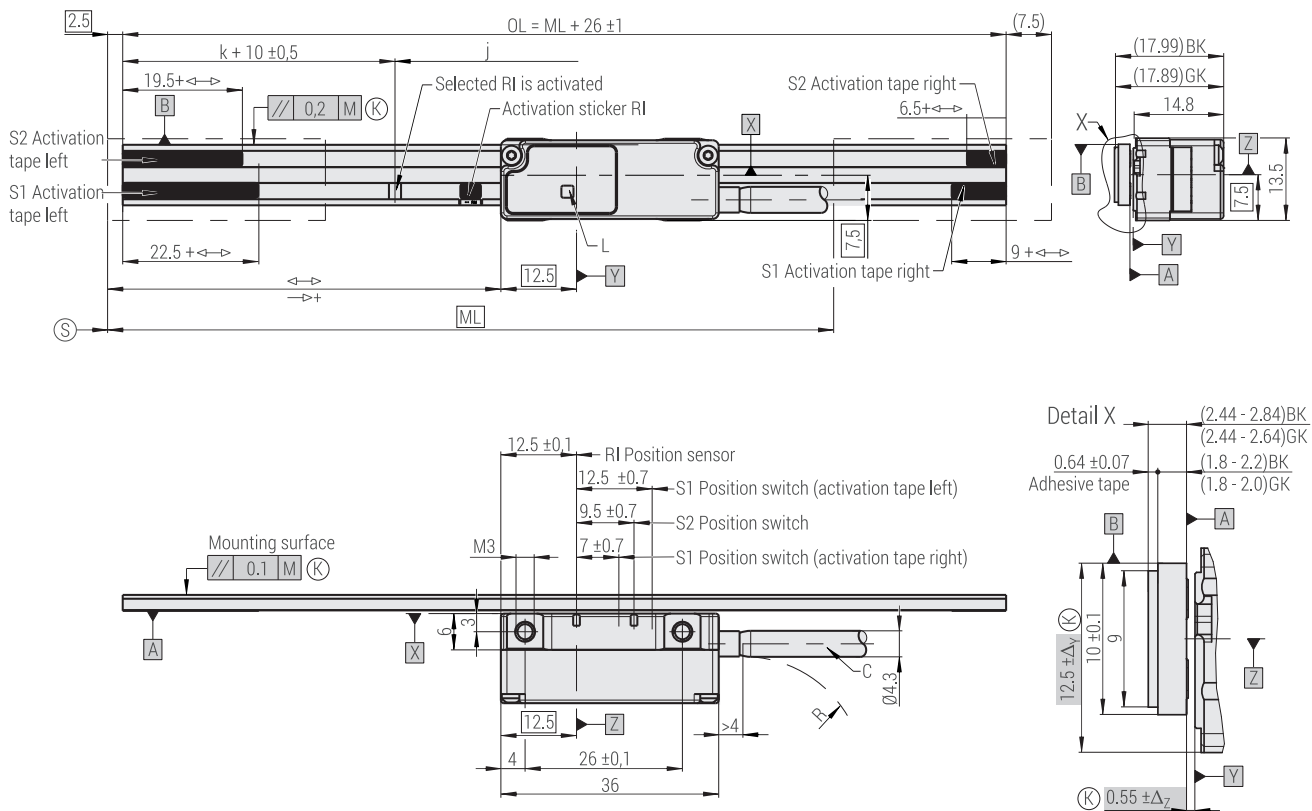
mm  
  
 Tolerancing ISO 8015  
 ISO 2768:1989 - m H  
 < 6 mm:  $\pm 0.2$  mm

# MS 15 GK, BK

- GK: Glass scale with adhesive tape
- BK: Glass ceramic scale with adhesive tape



Dimensions, mounting tolerances:



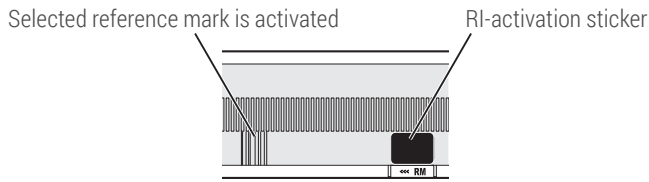
- M = Machine guideway
- ML = Measuring length
- OL = Overall length
- $\leftrightarrow$  = 0...ML
- $\rightarrow+$  = Direction of motion of the scanning head for ascending position values
- RI = Selectable reference mark(s)
- k = Any position of the selected reference mark starting from the beginning of the ML
- j = Additional reference marks selectable every 50 mm
- C = Cable
- $\textcircled{K}$  = Required mating dimensions
- L = LED function control
- R = Bending radius: stat.  $R \geq 8$  mm, dyn.  $R \geq 20$  mm
- $\textcircled{S}$  = Beginning of the measuring length
- S1, S2 = Switch signal
- BK = Glass ceramic scale with adhesive tape
- GK = Glass scale with adhesive tape

- Permissible position deviation scanning head – scale  $\textcircled{A} \textcircled{B}$
- $\Delta_y$  = Displacement,  $\pm 0.5$  mm
  - $\Delta_z$  = Gap tolerance,  $\pm 0.2$  mm
  - $\varphi_z$  =  $\pm 1.00$  mrad or  $\pm 0.06^\circ$  (yaw angle)
  - $\varphi_y$  =  $\pm 3.50$  mrad or  $\pm 0.20^\circ$  (pitch angle)
  - $\varphi_x$  =  $\pm 4.00$  mrad or  $\pm 0.23^\circ$  (roll angle)

mm  
 Tolerancing ISO 8015  
 ISO 2768:1989 – m H  
 < 6 mm:  $\pm 0.2$  mm

# REFERENCE MARK (RI)- AND SWITCH POINTS-SELECTION

## Reference mark (RI)-selection



## Selection of the switch points

$S1_L$  = Switch point signal S1 from the beginning of the measuring length ML

$S1_R$  = Switch point signal S1 before end of the measuring length ML

$S2_L$  = Switch point signal S2 from the beginning of the measuring length ML

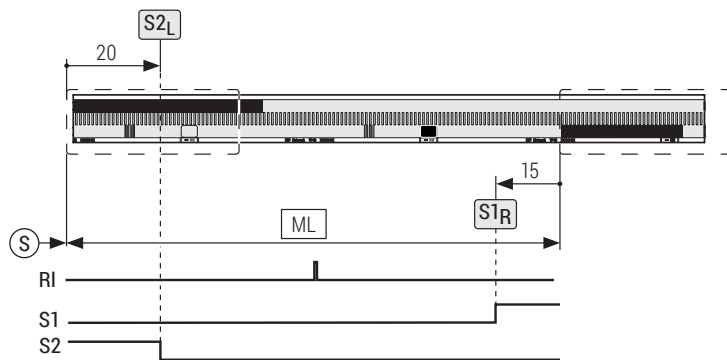
$S2_R$  = Switch point signal S2 before end of the measuring length ML

Ⓢ = Beginning of the measuring length ML

### EXAMPLE 1: LIMIT FUNCTION

$S1_R$  : 15 mm before end of ML

$S2_L$  : 20 mm from beginning of ML

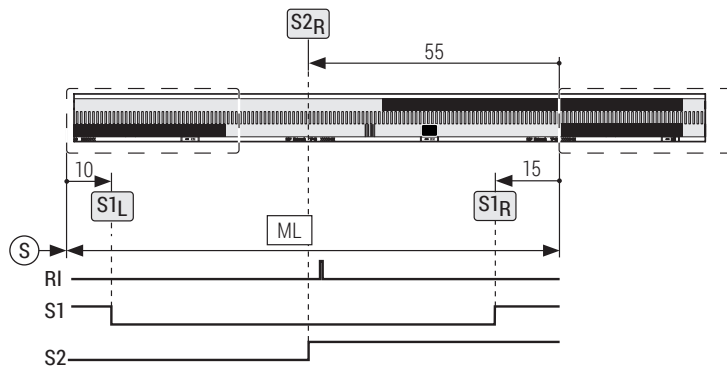


### EXAMPLE 2: LIMIT FUNCTION AND HOMING

$S1_L$  : 10 mm from beginning of ML

$S1_R$  : 15 mm before end of ML

$S2_R$  : 55 mm before end of ML



#### Note!

Dimensions and rules for activation tapes are described in the mounting instructions.

## INSPECTION OF FUNCTIONS

STATUS OF LED	INFORMATION	NOTE
<b>Without external test box</b>		
<b>Function-control main track</b>		
▪ LED displays GREEN	Counting signals very good	After successful mounting
▪ LED blinks GREEN	Counting signals good	At mounting not allowed → allowed during operation
▪ LED blinks RED	Counting signals out of tolerance → error	Check mounting, clean graduation carrier
<b>Function-control reference impulse RI</b>		<b>Only by passing the reference mark</b>
▪ LED blinks BLUE	RI within tolerance	
▪ LED blinks RED	RI out of tolerance	Check mounting, clean graduation carrier
<b>With external test box</b>		
<b>Function-control main track</b>		
▪ LED displays GREEN	Scanning head supplied with power	Evaluation of counting signals via LED not active
<b>Function-control reference impulse RI</b>		<b>Only by passing the reference mark</b>
▪ LED blinks BLUE	RI within tolerance	
▪ LED blinks RED	RI out of tolerance	Check mounting, clean graduation carrier

**Note!** If the scanning head passes a further reference mark within 0.5 s the information of the reference mark will not be stated by the function control. Thus the information of the incremental signals will also be displayed at high traversing speed and/or many reference marks.

## EXTERNAL TESTING DEVICE PWT 101

Even though the MS 15 linear encoders allow large mechanical mounting tolerances, it is recommended to control the function of counting signals and reference impulse.

The signals can be controlled directly via the integrated LED function-control or connected to an oscilloscope and checked for conformity with signal specifications. The last mentioned method requires some effort.

The PWT 101 is a testing device for checking the function and adjustment of RSF Elektronik encoders. At encoders with pin assignment according to RSF standard (compare page 05) the pinout adapter PA2 must be used additionally. At alternative pin assignments other pinout adapters could be necessary.

Thanks to its compact dimensions and robust design, the PWT 101 is ideal for mobile use. A 4.3-inch touchscreen provides for display and operation.

### Available functions

The performance range of the PWT 101 can be expanded by firmware update. Appropriate firmware files that can be imported to the PWT 101 through a memory card (not included in delivery) will be made available at [www.heidenhain.de](http://www.heidenhain.de).



## FURTHER PRODUCTS



### MCR 15 | MCS 15

*Absolute modular angle encoders with small dimensions*

- Diverse serial interfaces
- Status display directly at the scanning head via LED function
- Easy mounting as a result of large mounting tolerances
- High insensitivity against contaminations
- Possible drum diameter (TTR): 50.00 mm to 350.23 mm (outside)
- Possible scanning diameter (MBR): 59.93 mm to 350.23 mm (outside)
- Steel tape scale (MCS) from  $\varnothing$  75 mm



### MCR 16 | MCS 16

*Absolute modular angle encoders with small dimensions*

- Diverse serial interfaces
- Status display directly at the scanning head via LED function
- Easy mounting as a result of large mounting tolerances
- High insensitivity against contaminations
- Possible drum diameter (TTR): 75.06 mm to 350.23 mm (outside)
- Possible scanning diameter (MBR): 75.06 mm to 350.23 mm (outside)
- Steel tape scale (MCS) from  $\varnothing$  75 mm



### MSR 15 | MSS 15

*Incremental modular angle encoders with small dimensions*

- Quality of the scanning signals is directly visible at the scanning head via a tricolored LED function
- Easy mounting as a result of large mounting tolerances
- High insensitivity against contaminations
- Possible drum diameter (TTR): 50.00 mm to 350.23 mm (outside)
- Possible scanning diameter (MBR): 59.93 mm to 350.23 mm (outside)
- Steel tape scale (MSS) from  $\varnothing$  75 mm



### MSR 45

*Modular angle encoders with steel tape scale - various versions*

- Full-circle or segment version
- Grating period: 200  $\mu$ m
- Accuracy of the grating (stretched):  $\pm$ 30  $\mu$ m/m
- High permissible rotational speed resp. circumferential speed
- Integrated subdividing: up to times 100
- Possible diameter: Full-circle from  $\varnothing$  146.99 mm  
Segment from  $\varnothing$  150 mm



### MC 15

*Absolute linear encoders with status display*

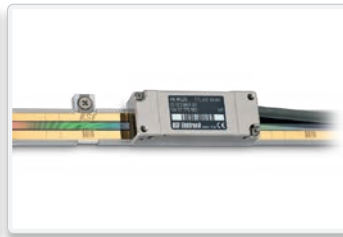
- Diverse serial interfaces
- Status display directly at the scanning head via LED function
- Easy mounting as a result of large mounting tolerances
- High insensitivity against contaminations
- Max. measuring length  
Steel tape scale: 10 000 mm



### MS 14

*Exposed linear encoder with integrated mounting control*

- Easy mounting; no test box or oscilloscope needed
- Quality of the scanning signals is directly visible at the scanning head via a tricolored LED function
- Position of reference mark selectable by customer
- High insensitivity against contamination
- High permissible traversing speed
- Integrated subdividing: up to times 200
- Max. measuring length  
Steel tape scale: 10 000 mm



### MS 25

*Exposed linear encoder with and without integrated mounting control*

- Easy mounting; no test box or oscilloscope needed
- Quality of the scanning signals is directly visible at the scanning head via a tricolored LED function
- Two independent switch tracks for individual special functions
- Position of reference mark selectable by customer
- High insensitivity against contamination
- High permissible traversing speed
- Integrated subdividing: up to times 200
- Max. measuring length  
Glass scale: 3140 mm  
Steel tape scale: 20 000 mm



### MS 45

*Exposed scanning linear encoders with integrated mounting control*

- Easy mounting; no test box or oscilloscope needed
- Quality of the scanning signals is directly visible at the scanning head via a tricolored LED function
- Flat dimensions
- Easy mounting due to large mounting tolerances
- High insensitivity against contamination
- High permissible traversing speed
- Integrated subdividing: up to times 100
- Max. measuring length:  
Steel tape scale: 30 000 mm

## DISTRIBUTION CONTACTS

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